

Вычислим моменты инерции

```
In[169]:= Cz = m * r^2 / 2
          Cxy = m * (h^2 / 12 + r^2 / 4)
```

Гирокопический момент

```
In[171]:= Hg = Cz * ω
```

Обобщенные координаты

```
In[172]:= s = D[β[t], t]
          s1 = D[α[t], t]
          s2 = D[γ[t], t]
```

Силы, действующие по осям

```
In[175]:= fx = 0
          fy = (Hg s1 - d s) Cos[β[t]]
          fz = 0
In[178]:= fxyz = {{fx}, {fy}, {fz}} // MatrixForm
```

Кинетическая энергия

```
In[179]:= Tk = Cxy * s^2 / 2 + Cxy * s1^2 / 2 + Cz * (ω + s2)^2 / 2
```

Запись уравнений Лагранжа

```
In[180]:= wx = Integrate[fx, α[t]]
          wy = Integrate[fy, β[t]]
          wz = Integrate[fz, γ[t]]
In[183]:= qxyz = {D[wx, α[t]], D[wy, β[t]], D[wz, γ[t]]}
In[184]:= ddTkDqdt = {D[D[Tk, s1], t], D[D[Tk, s], t], D[D[Tk, s2], t]}
In[185]:= dTkDq = {D[Tk, α[t]], D[Tk, β[t]], D[Tk, γ[t]]}
```

```
In[186]:= df = ddTkDqdt - dTkDq - qxyz
In[187]:= df = ReplaceAll[df, D[s1, t] → D[q11[t], t]]
```

Представление в форме Коши

```
In[188]:= m1 = {Solve[q11[t] - D[α[t], t] == 0, D[α[t], t]],
           Solve[Flatten[df[[1, 1]]] == 0, D[q11[t], t]]} // MatrixForm
In[189]:= df = ReplaceAll[df, {D[β[t], t] → q21[t], β[t] → q22[t], D[β[t], {t, 2}] → D[q21[t], t]}]
In[221]:= m2 = {{q21[t] - D[β[t], t]}, {D[q22[t], t] - D[β[t], t]}, {Flatten[df[[2, 1]]]}} // MatrixForm
```

```

In[223]:= 
m2k =
{Solve[q21[t] - D[β[t], t] == 0, D[β[t], t]], Solve[D[q22[t], t] - D[β[t], t] == 0, D[q22[t], t]],
Solve[Flatten[df[[2, 1]]] == 0, D[q21[t], t]]} // MatrixForm

In[224]:= 
df = ReplaceAll[df, {D[s2, t] → D[q32[t], t]}]

In[226]:= 
m3 = {Solve[q31[t] - D[γ[t], t] == 0, D[γ[t], t]],
Solve[Flatten[df[[3, 1]]] == 0, D[q32[t], t]]} // MatrixForm

```

Ввод упрощений

```

In[227]:= 
ReplaceAll[m1, D[α[t], t] → 0]
ReplaceAll[m3, D[γ[t], t] → 0]
m2 = ReplaceAll[m2, {Cos[q22[t]] → 1, D[q21[t], t] → 0, D[α[t], t] → Ω}]

```

Решение

```

In[230]:= 
resh0 = Flatten[Solve[Flatten[m2[[1, 3]]] == 0, q21[t]]]
Clear[β]
m2 = ReplaceAll[m2, resh0[[1]]]
resh = Flatten[DSolve[{m2[[1, 1]][[1]] == 0, β[0] == 0}, β[t], t]]

```

Подстановка

```

In[234]:= 
resh = ReplaceAll[resh, {m → dr^2 Pi / 4 * h * ro, r^2 → dr^2 / 4}]
resh = ReplaceAll[resh, {dr → 2, h → 1, d → 10000, ω → 20000 2 Pi / 60, ro → 7.8}]
resh = ReplaceAll[resh, Ω → 0.2]

```

```

In[204]:= 
Построение граффика

```

```

In[237]:= 
tn = 0
tk = 5

```

```

In[239]:= 
Plot[resh[[1, 2]], {t, tn, tk}]

```

```

In[240]:= 
ReplaceAll[resh, {t → tk}]

```